



# Intercalibration of SMOS and Aquarius over land, ice and ocean.

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#### SMOS & Aquarius Science Workshop IFREMER, Brest.



#### Introduction



Only 2 current missions provide L-Band global measurements of brightness temperatures Primary objectives are soil moisture and ocean salinity retrieval.

Also used for freeze/thaw detection, sea ice assessment

SMOS since November, 2<sup>nd</sup> 2009

4 Stokes, incidences [0°,65°]

Radiometric interferometer

Calibration based on internal noise diodes and deep sky

Absolute brightness temperature accuracy

Temporal stability short/long term

Directional stability Within field of view, special care given to extended alias free 1st reprocessing data set Aquarius since June, 10<sup>th</sup> 2011

3 Stokes, incidences 28°, 38°, 46°

2.5 m reflector and feed horns Calibration based on internal noise diode and vicarious

High sensitivity Long term drift beam-to-beam consistency Processing v2.0

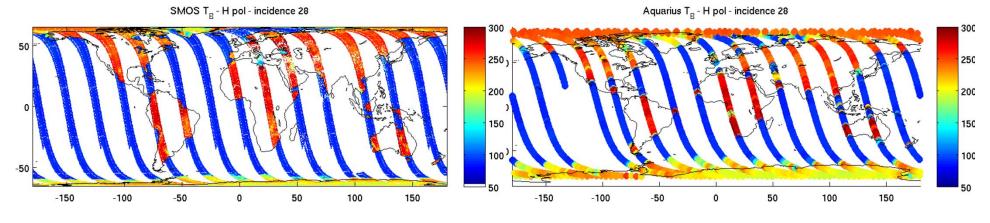




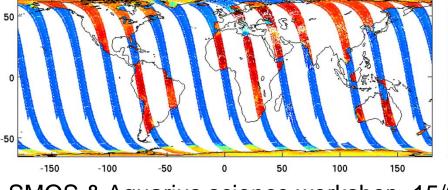


#### Brightness temperature maps

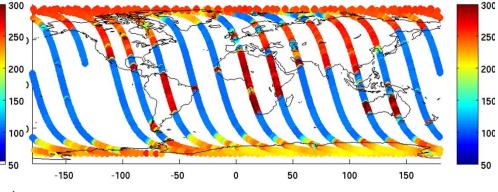
At the global scale, comparison is far too coarse because of too different conditions at acquisition time















### Howto compare TBs

Comparison methods must account for

Geometry of acquisition

Careful selection in SMOS directional sampling covers Aquarius incidences

Footprint, antenna patterns, sampling

Homogeneous areas

Taking advantage of SMOS capabilities to simulate Aquarius measurements

Surface change

Stable zones

Simultaneous observations

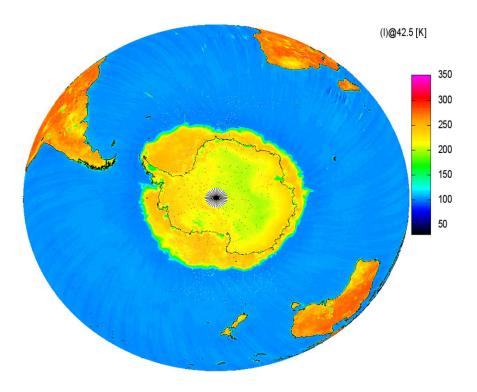




### Antarctica around Dome Concordia

Antarctic plateau around Dome C appears a very good candidate for stability monitoring and across fov consistency check On-ground measurement campaign took place in 2009, 2010

New campaign on-going



ascBWS\_20110518T083604\_20110524T232925/BWS.txt - 1st Stokes

E. Slominska





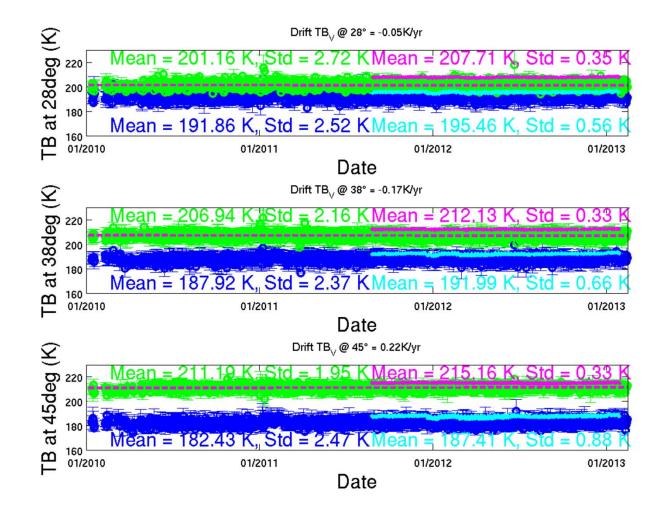
## Long term stability over Antarctica

Both instruments show good long term stability

- Difference in sensitivity clearly evidenced
- Summer surface changes induce noisier behavior at V polarization

Mean biases

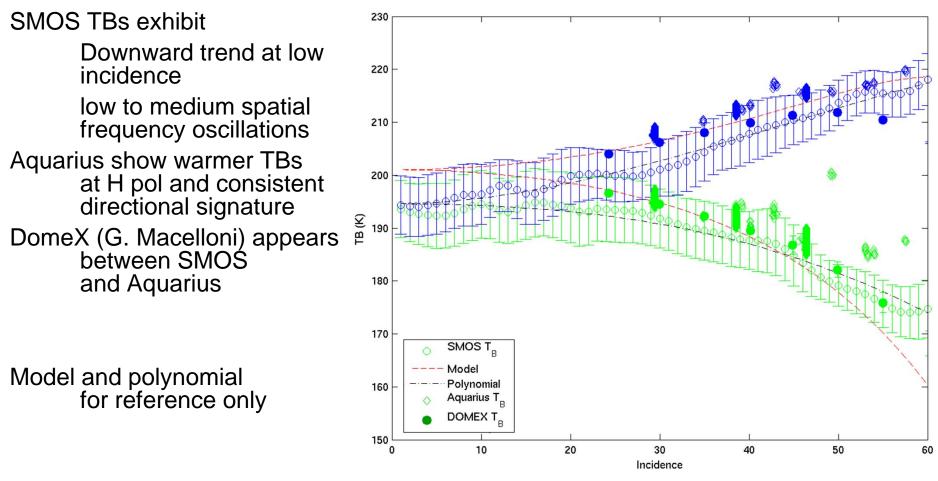
	Н	V
inner	6.11	5.54
middle	5.12	3.40
outer	5.54	3.99







#### **Directional behavior**



Hallikainen model (one layer, Tsnow=-54)



### Aquarius co-locations

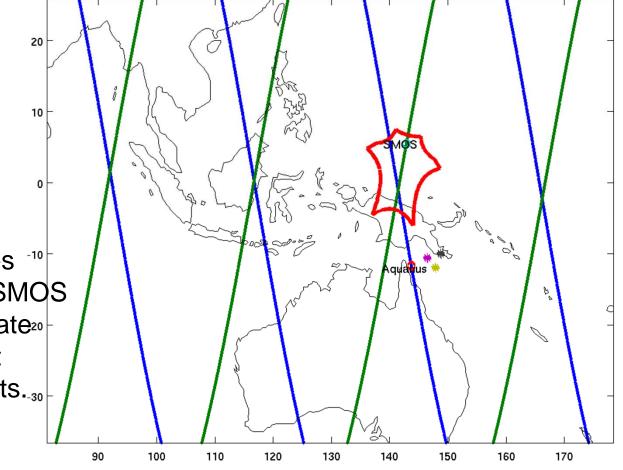


Every 3 days, SMOS over flies Aquarius in 2 to 4 occasions Over 500 days in 2011-2012, over 750 co locations where selected

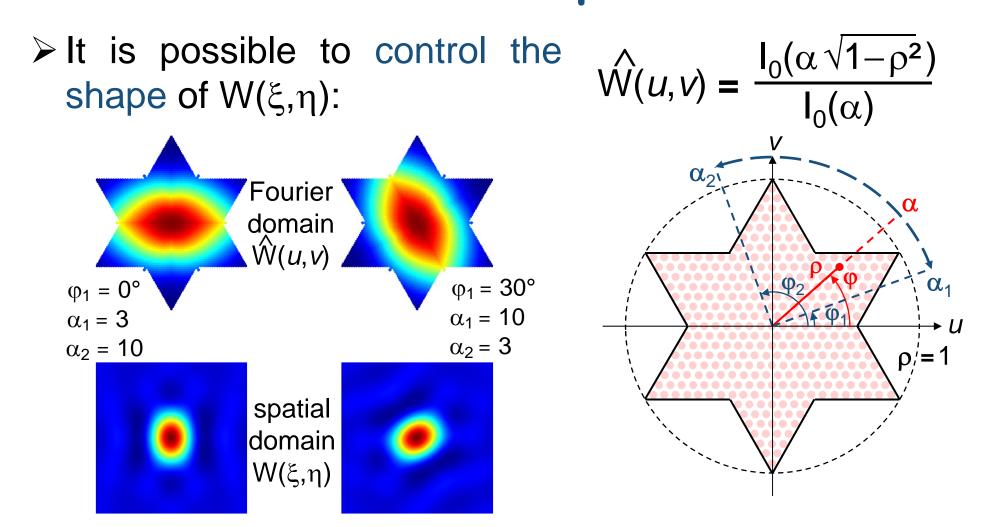
Over fly: Seen from ground apparent distance less than 2.5°

Over collocations, spatial frequencies <sup>-10</sup> as measured by SMOS are used to simulate<sup>20</sup> -Aquarius footprint and measurements.<sub>-30</sub> -

SMOS & Aquarius s



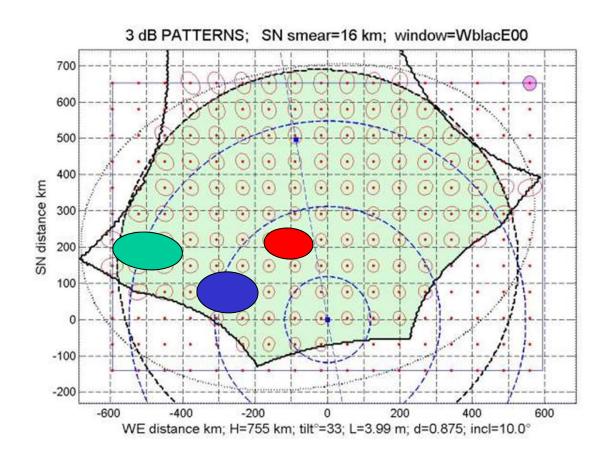








# AQUARIUS in SMOS



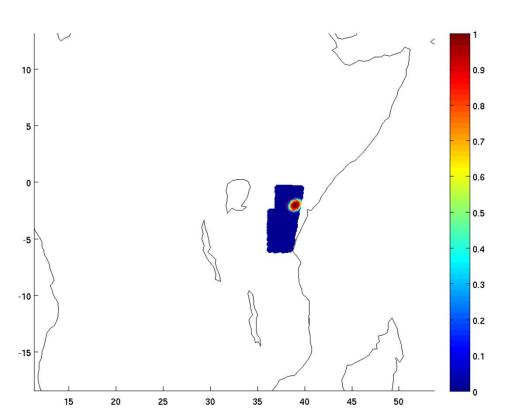




#### Aquarius-like SMOS TBs

Equivalent to convolution of SMOS brightness temperatures with Aquarius antenna footprint

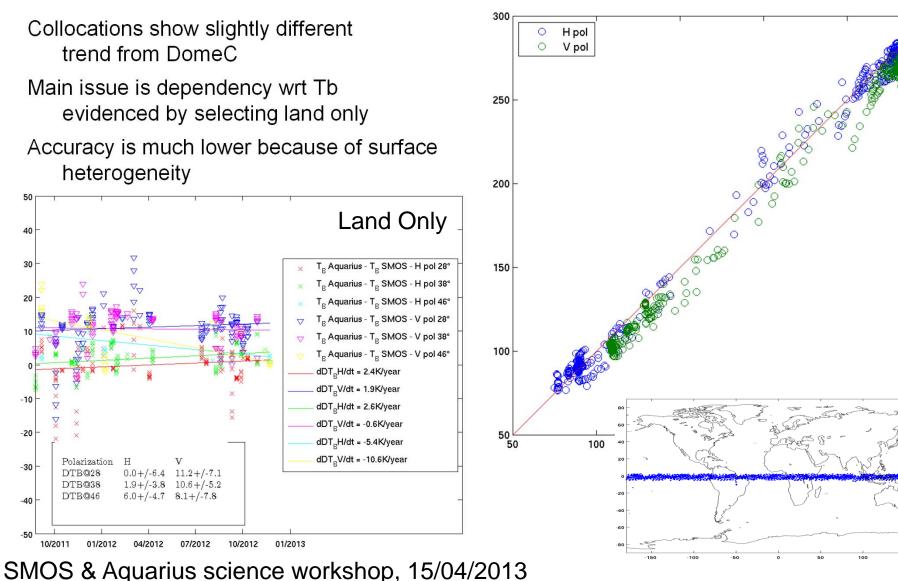
Could be improved by using actual Aquarius antenna pattern...







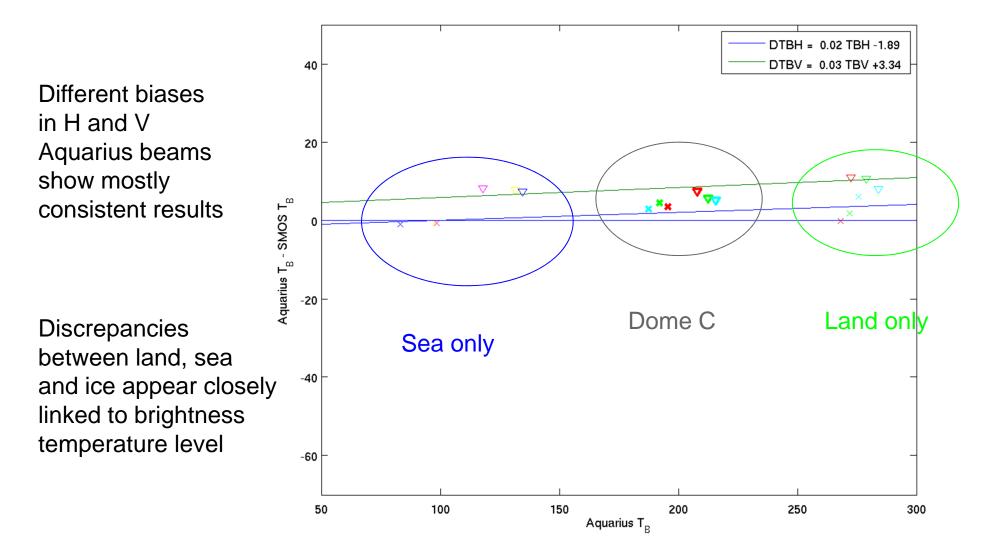
# SMOS-Aquarius comparison over all surfaces







#### All sites summary





## Summary



SMOS Tbs are consistently lower than Aquarius Tbs v2.0 Biases vary from 0-2.5K over ocean up to 6-9K over land, with a linear increase with Tb.

- Dome C and Collocations give access to full range of temperatures for intercalibration
- Yet not enough to characterize proper biases in each instrument.
- Comparison with ground measurements and model of reference might help. And DomeC is a very good candidate.
- But will not allow to explore the whole range.
- Standard definition will need various levels of temperature
- to cover for land, ice and ocean thematics. SMOS & Aquarius science workshop, 15/04/2013



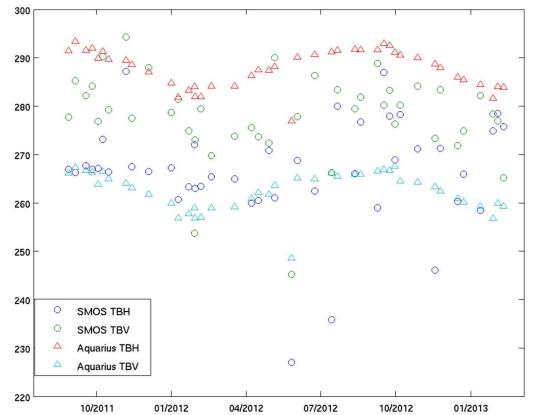


### Yet other comparisons...

Saharan desert, although not stable in time could still be used for intercomparison on a daily basis.

Southwest Libya offers a good example





Work in progress... SMOS & Aquarius science workshop, 15/04/2013